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FIG. 1

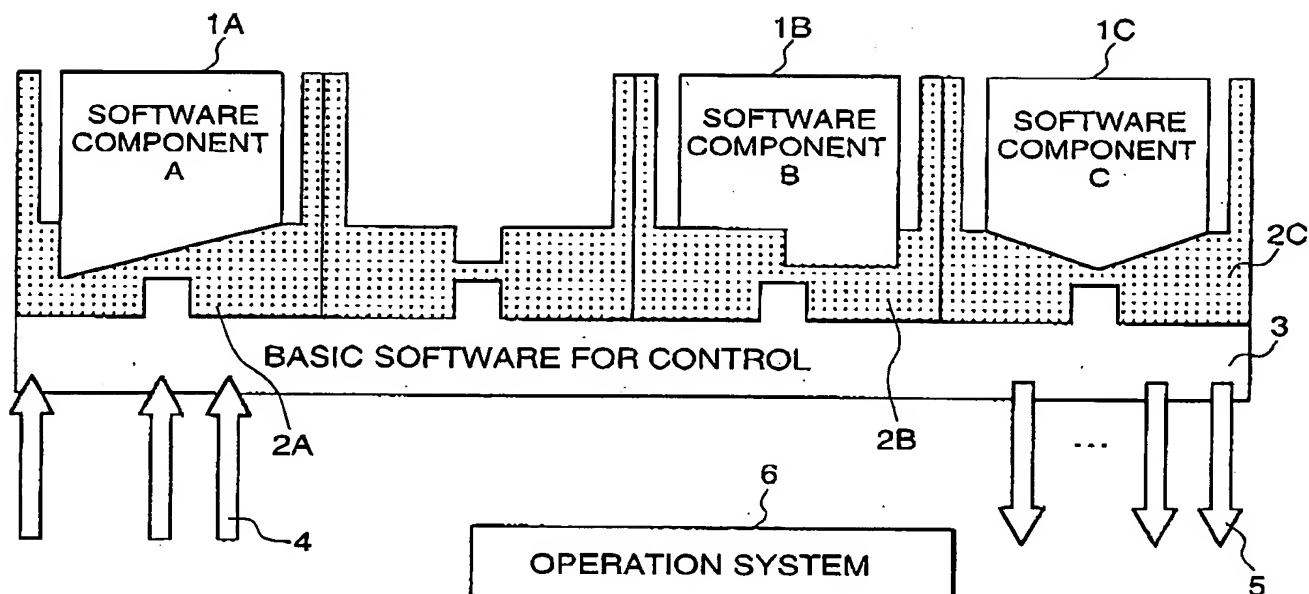
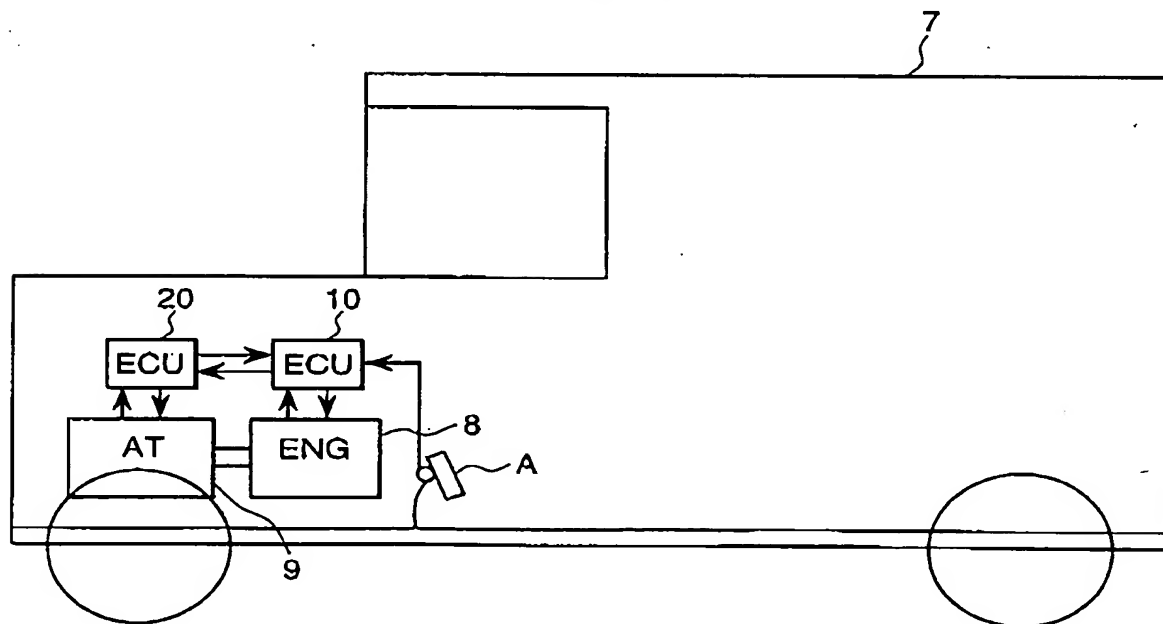
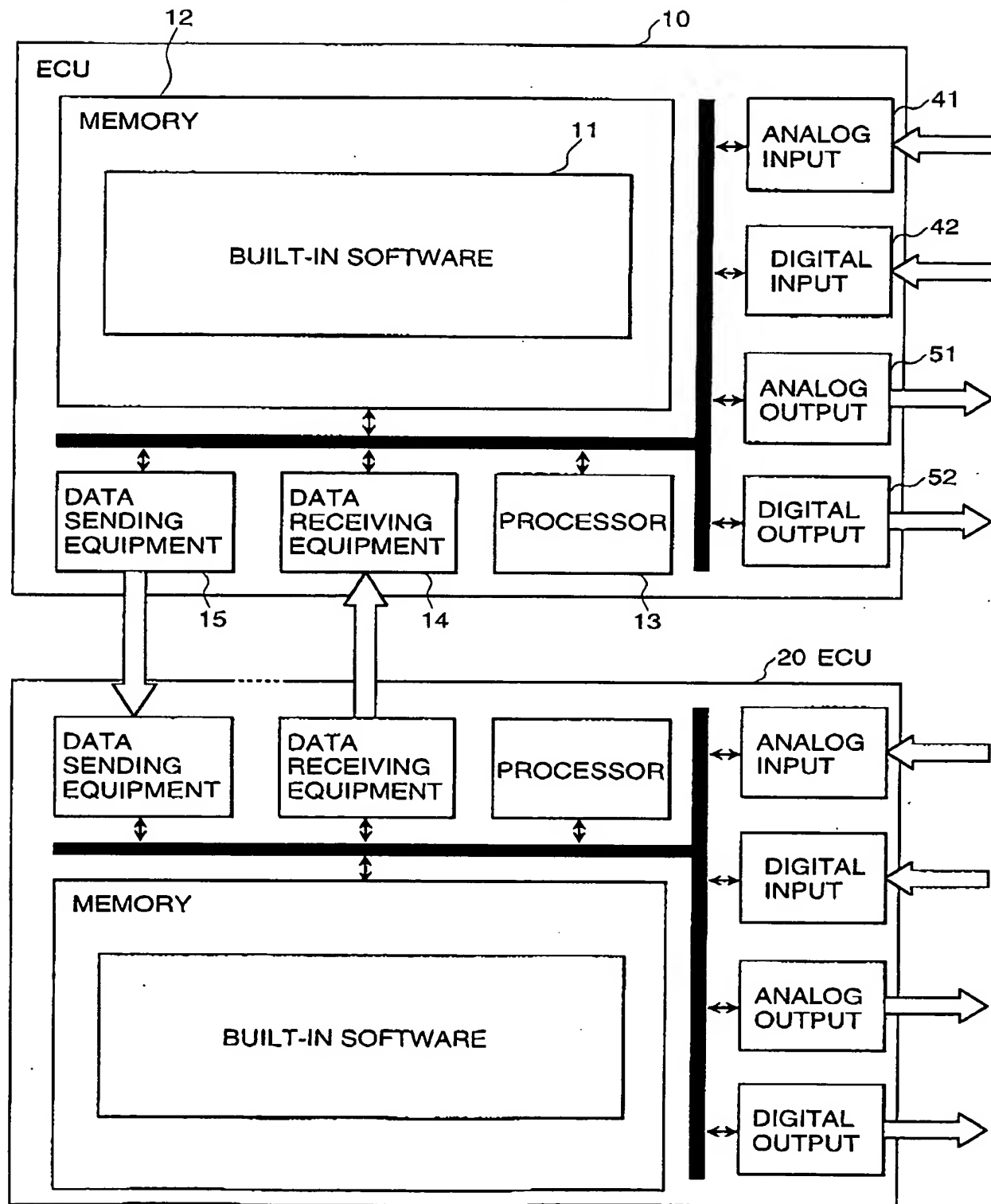


FIG. 2



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FIG. 3



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FIG. 4

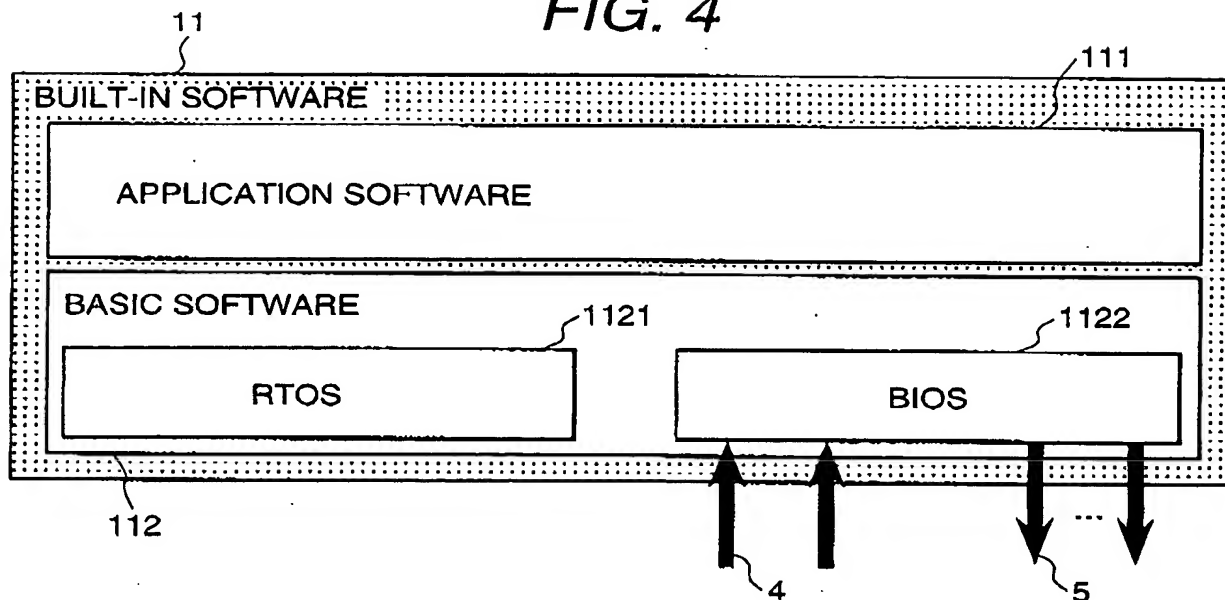
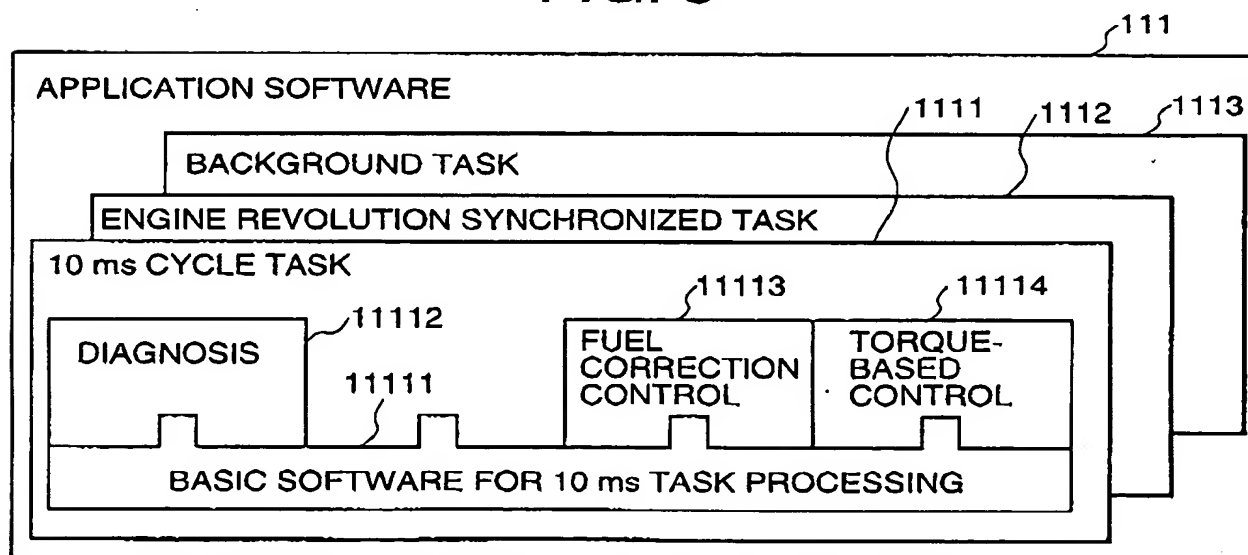


FIG. 5



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FIG. 6

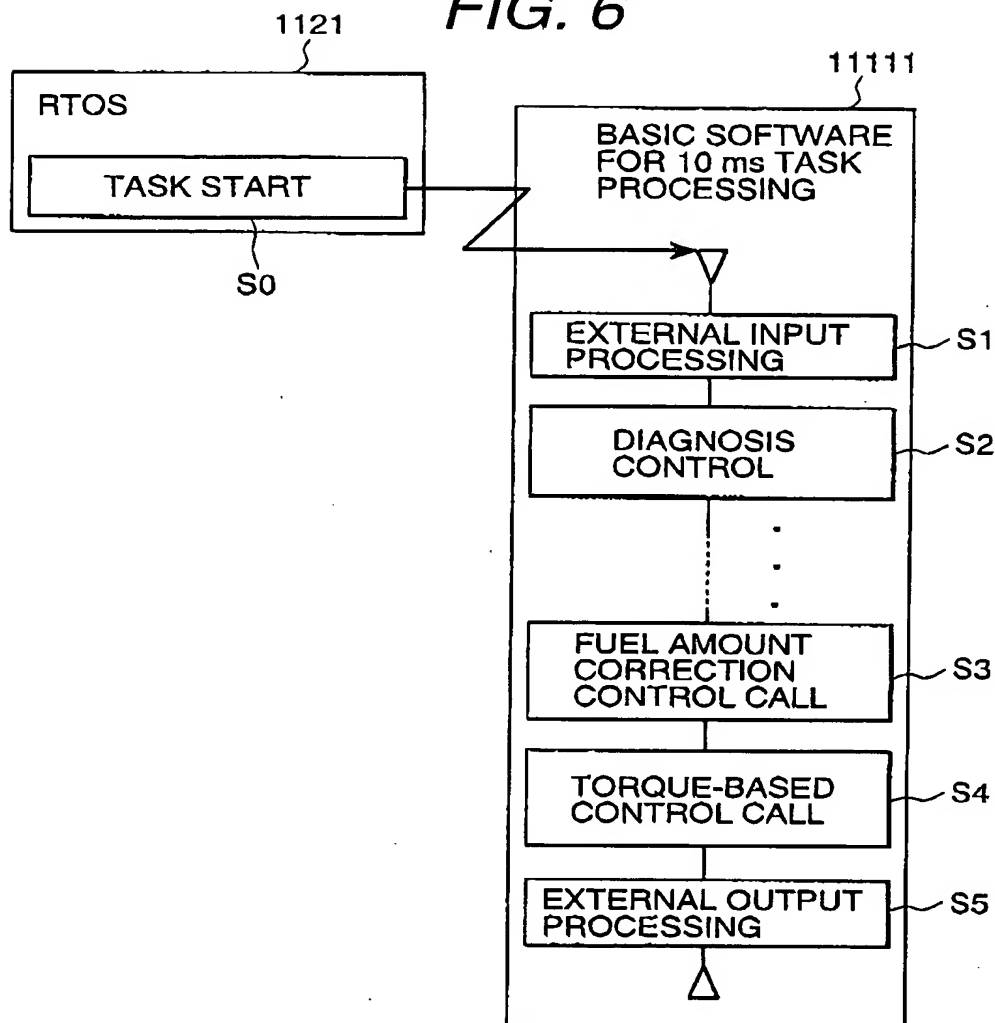
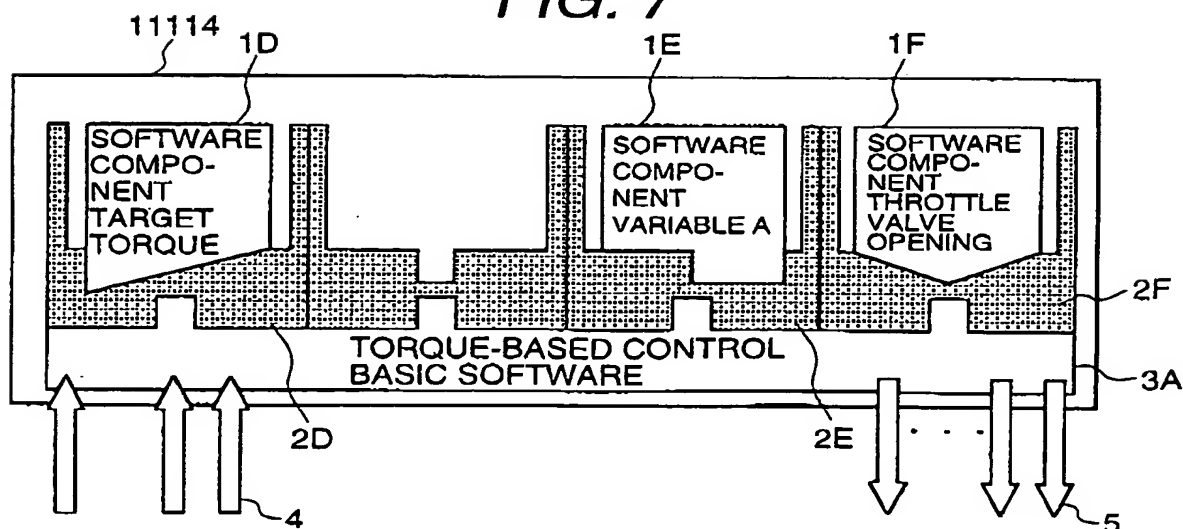


FIG. 7



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FIG. 8

```
extern void TVO_Calculate(unsigned short TargetTorque,  
                          ...,  
                          unsigned short Variable_A,  
                          unsigned short *TVO  
                          );
```

C11

```
/* EOF */
```

```
void TVO_Calculate(      unsigned short TargetTorque,  
                        .  
                        .  
                        .  
                        unsigned short Variable_A,  
                        unsigned short *TVO
```

C12

```
)  
{
```

```
    .  
    .  
    .
```

```
    *TVO=TargetTorque*Kt+Variable_A*Ka;
```

```
}
```

```
/* EOF */
```

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FIG. 9

```

unsigned short TVO;
/* EOF*/

```

C21

```

#define TVO_Get() TVO
extern unsigned short TVO;
/* EOF*/

```

C22

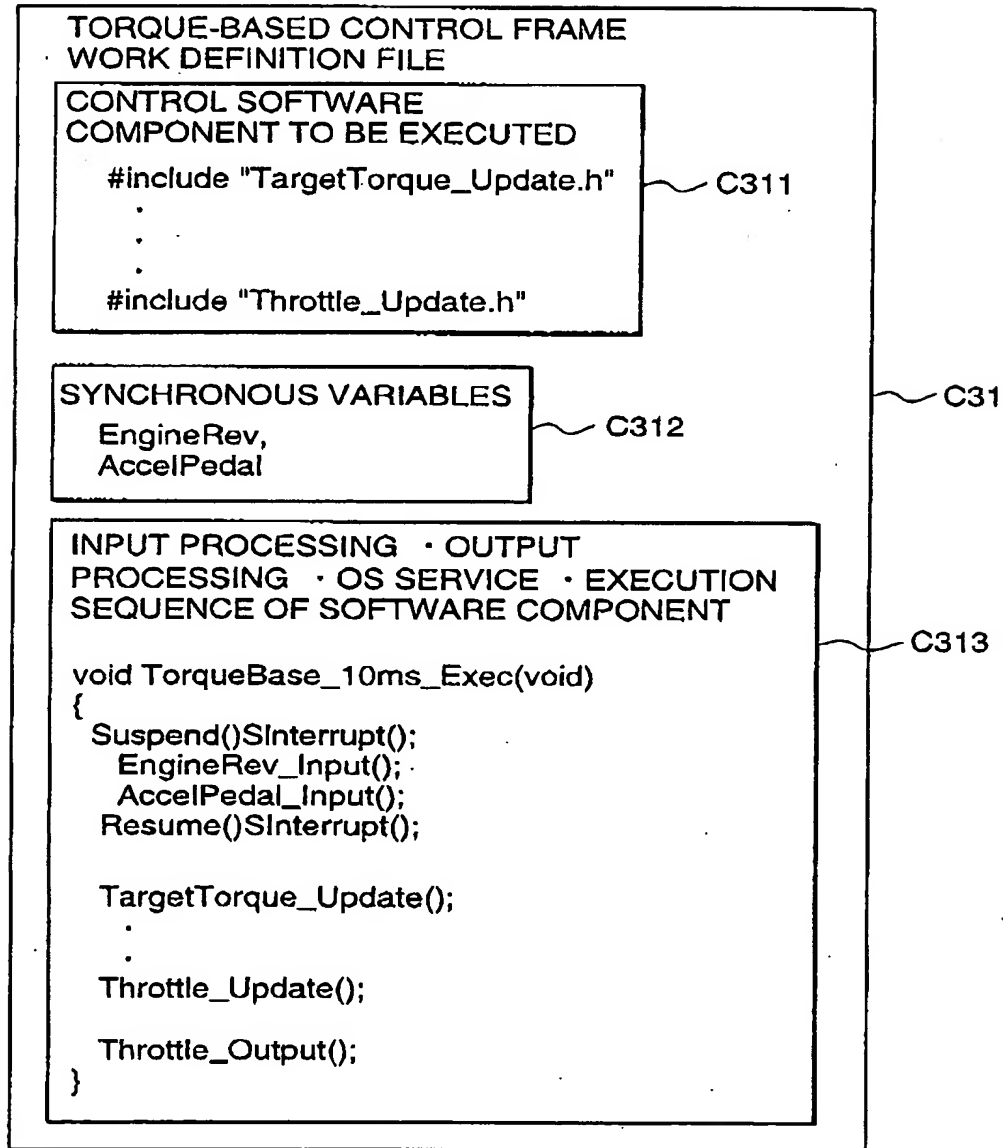
```

#include "TVO.h"
#include "TargetTorque.h"
.
.
.
#include "variableA.h"
#define TVO_Update() ¥
{¥
    TVO_Calculate(¥
        TargetTorque_Get()¥
        .
        .
        .
        variableA_Get(),¥
        &TVO¥
    )¥
}
/*EOF*/

```

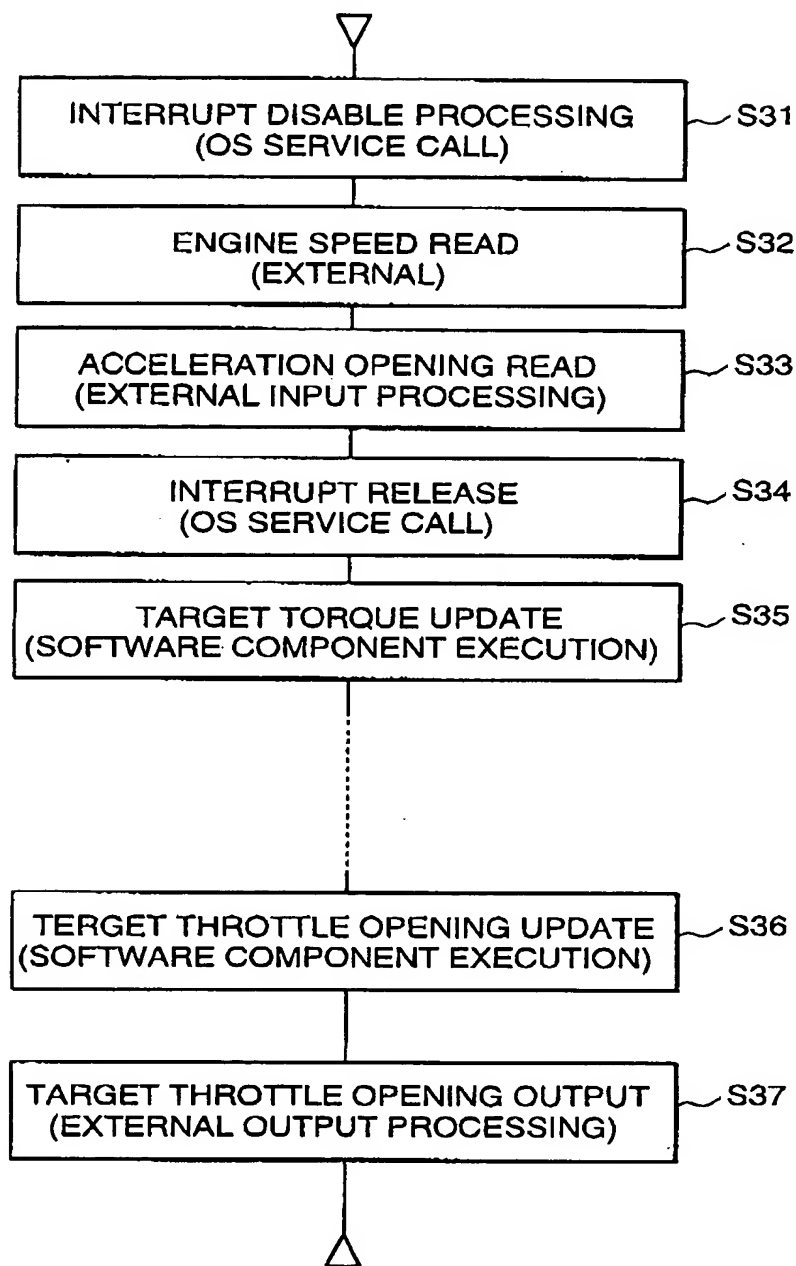
C23

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FIG. 10

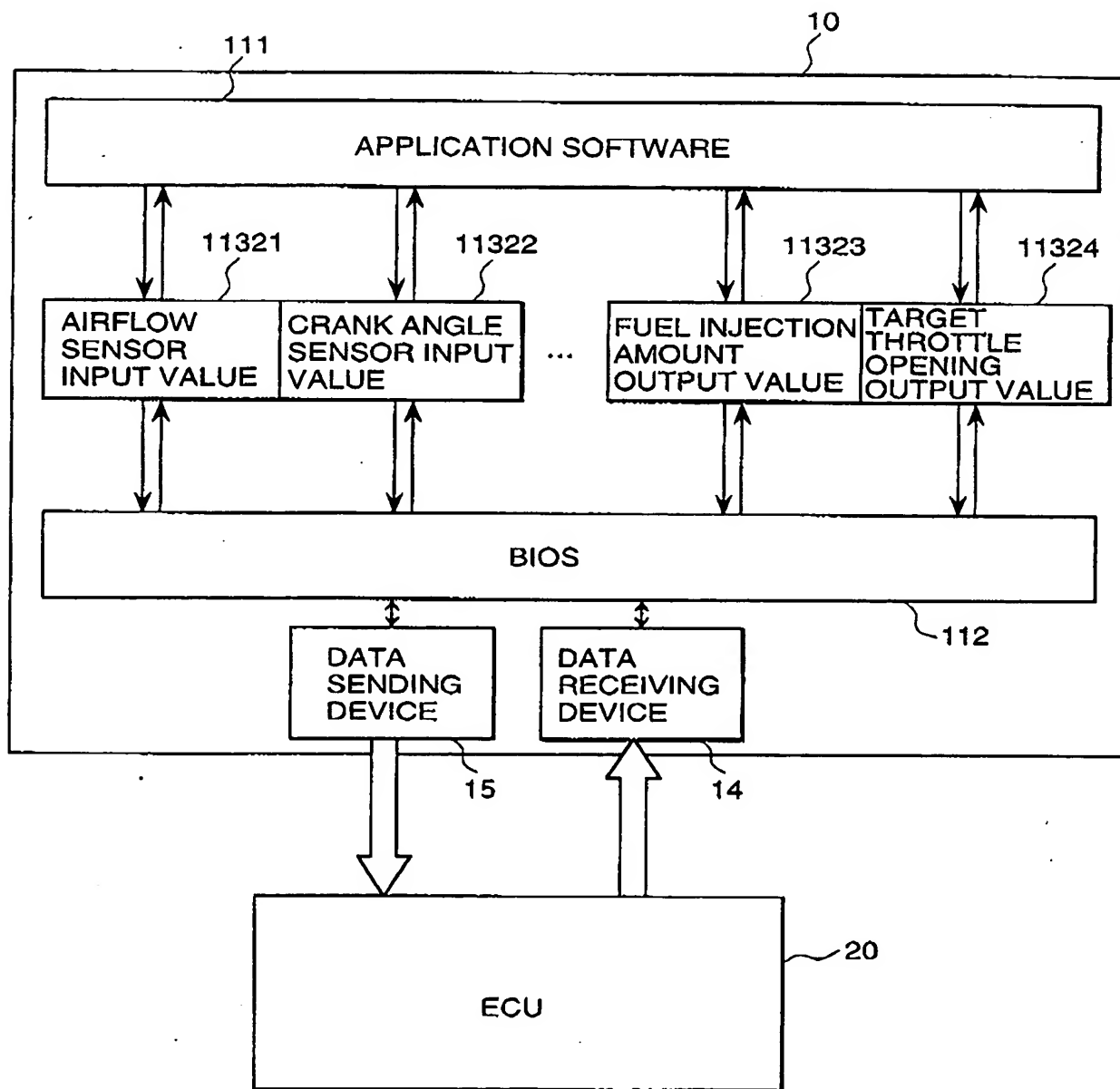
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FIG. 11

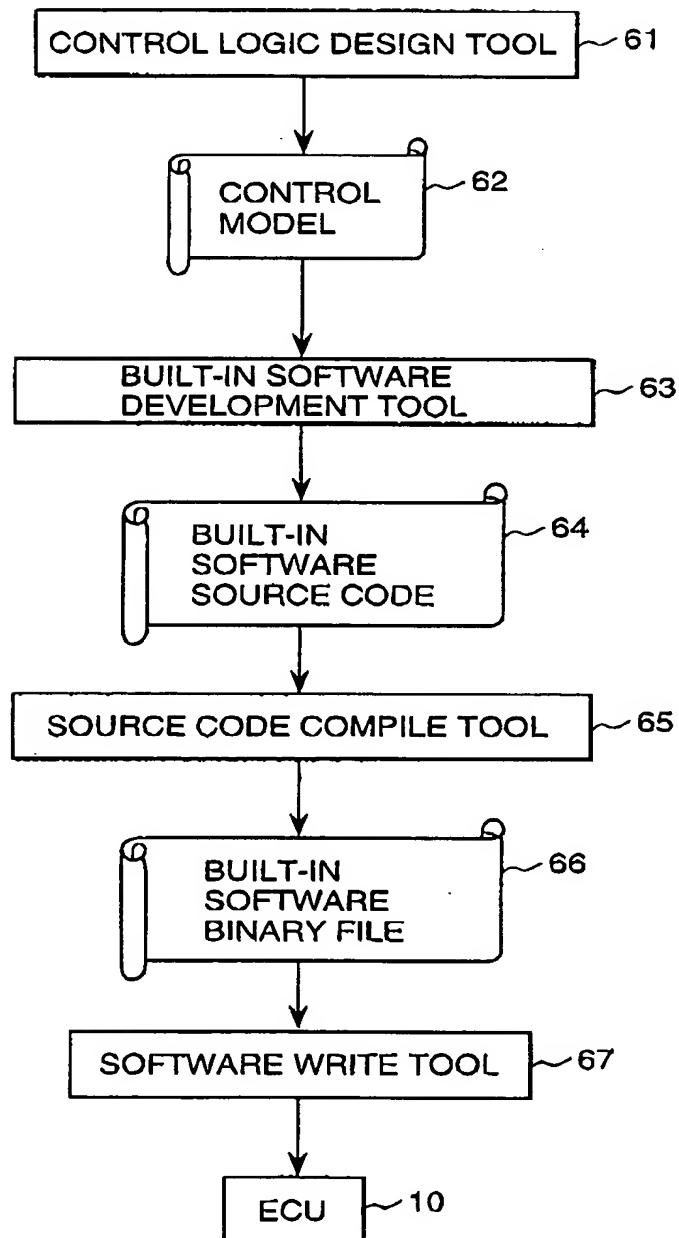


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FIG. 12

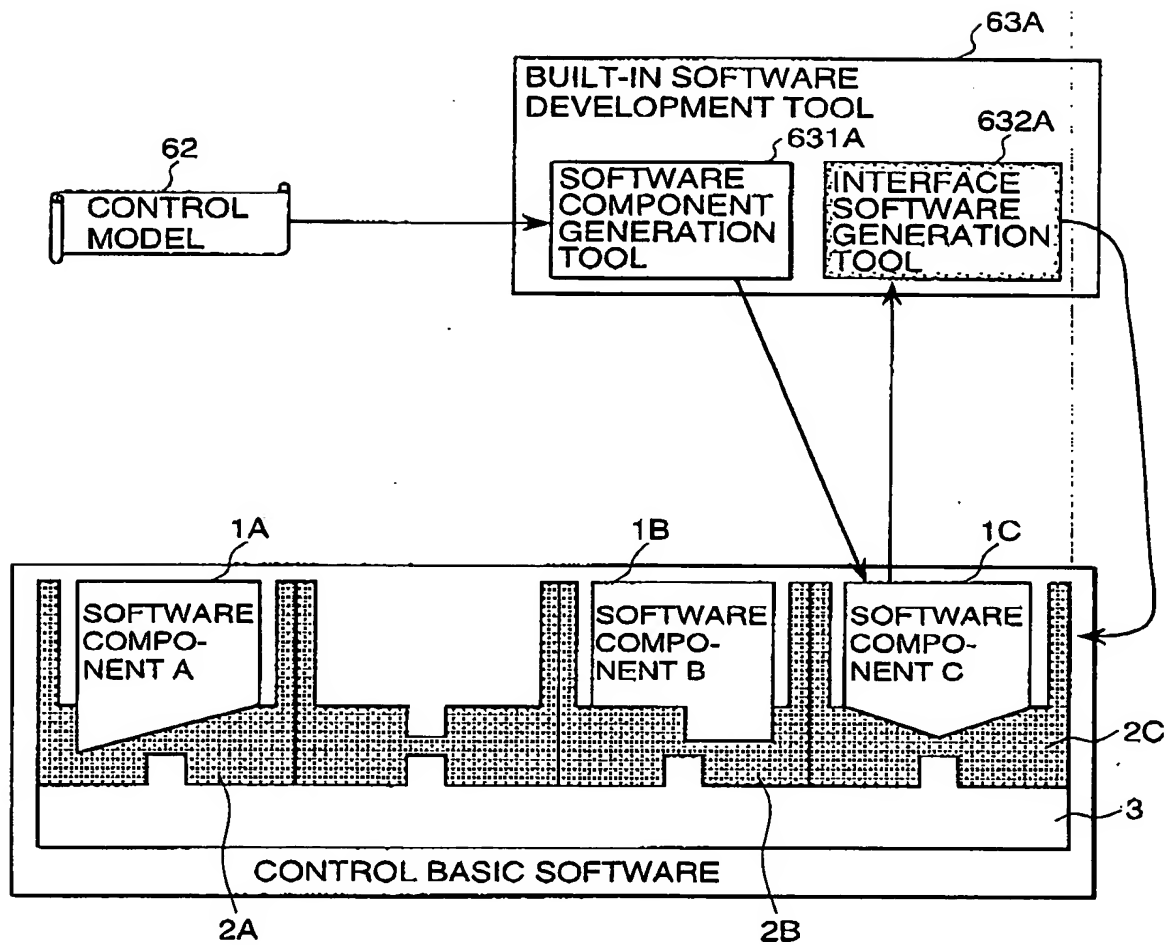


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FIG. 13

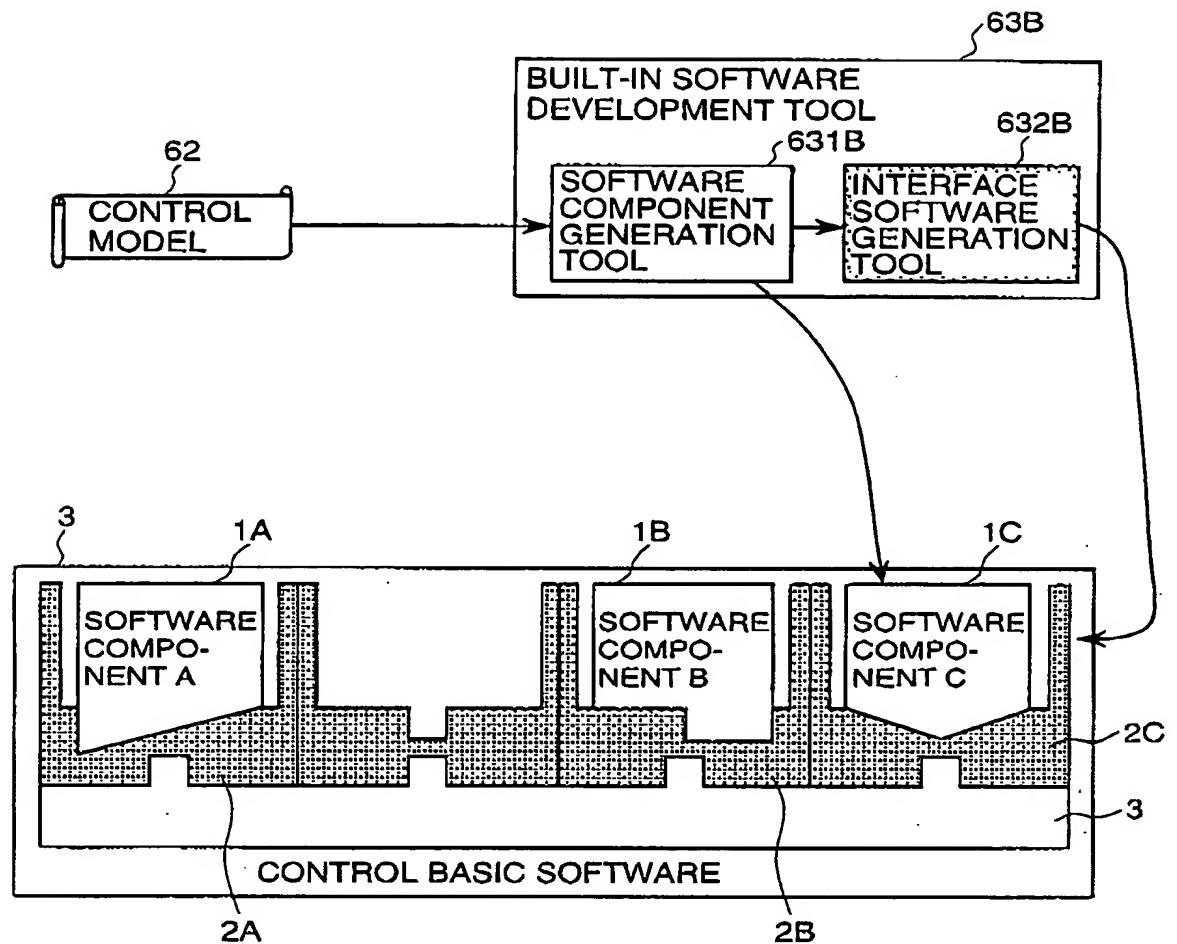
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FIG. 14



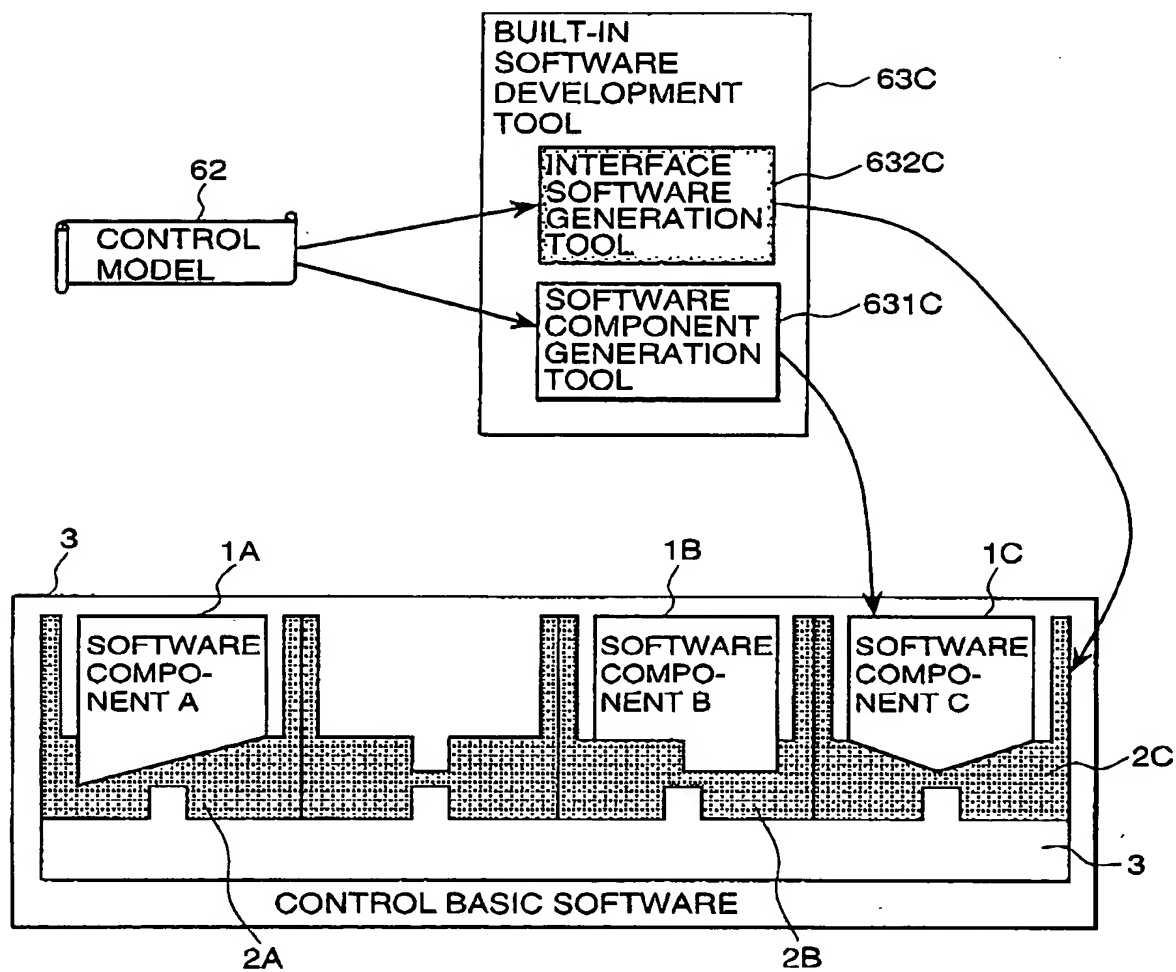
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FIG. 15



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FIG. 16



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FIG. 17

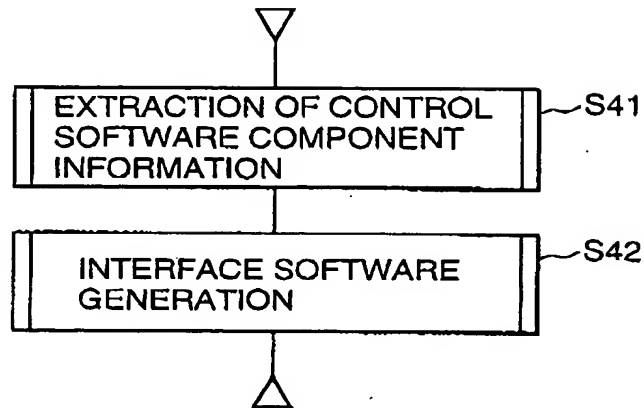
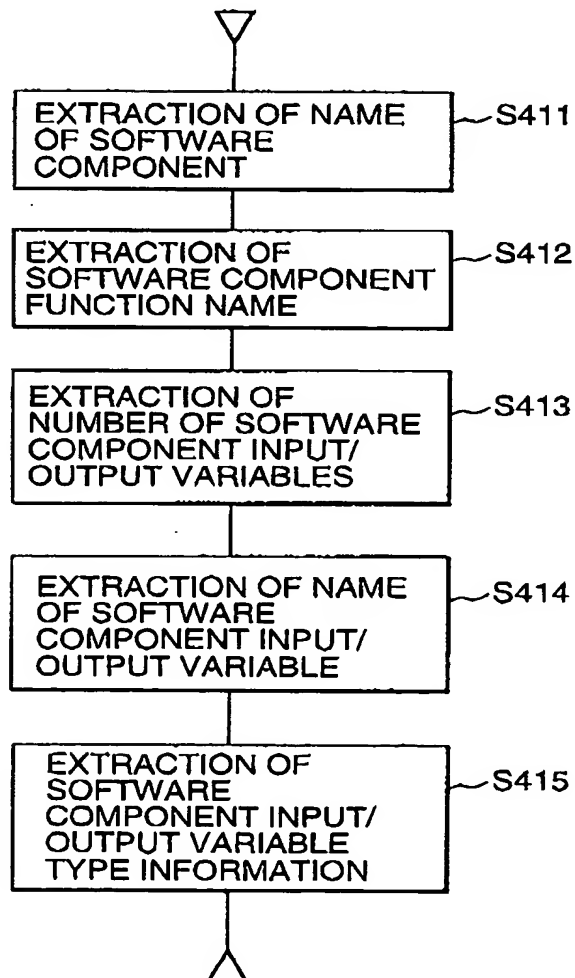


FIG. 18



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FIG. 19

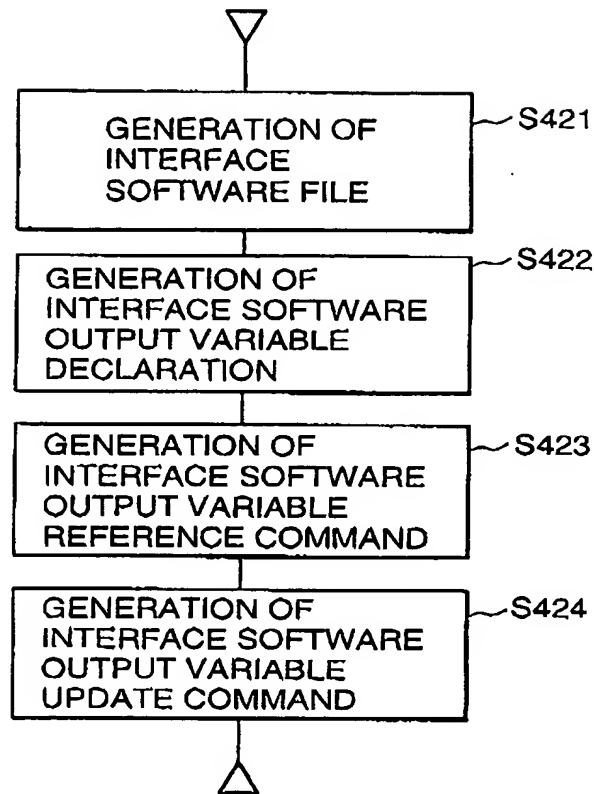
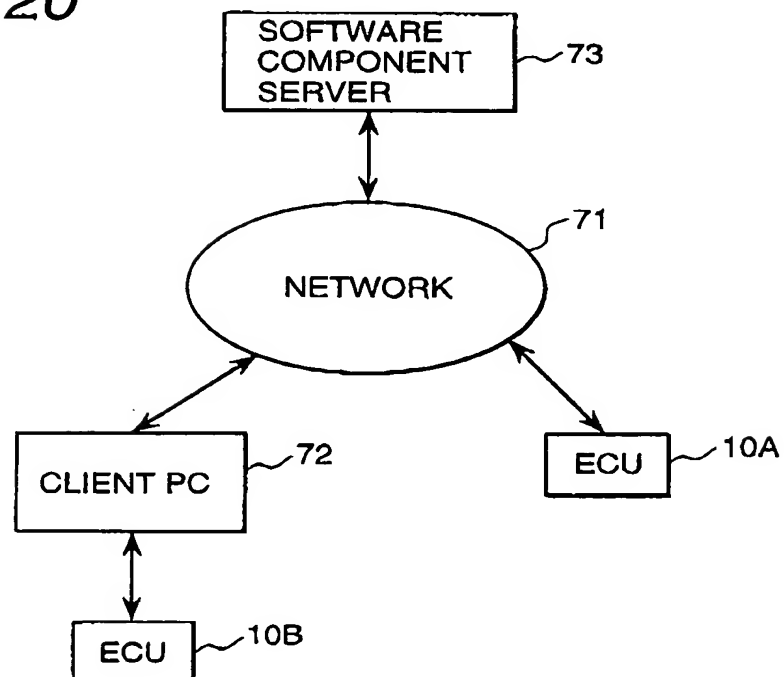


FIG. 20



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FIG. 21